

Finishing Bases:

Definition: A *minimal spanning set* of V is a set that spans V but does not span V if a single vector is removed.

So the set $\mathcal{S} = \{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ is a minimal spanning set of V if \mathcal{S} spans V but the sets $\{\mathbf{v}_1, \mathbf{v}_2\}$, $\{\mathbf{v}_1, \mathbf{v}_3\}$ and $\{\mathbf{v}_2, \mathbf{v}_3\}$ do not.

Definition: A *maximal linearly independent* set in V is a set that is LI, but becomes LD if a single additional vector in V is included.

So the set $\mathcal{S} = \{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ is a maximal linearly independent set in V if \mathcal{S} is LI but the set $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \mathbf{x}\}$ is LD for ANY $\mathbf{x} \in V$.

Definition: A *basis* for vector space V is a spanning set for V that is also a linearly independent set.

Definition: If a set of n vectors forms a basis of the vector space V then the *dimension* of V , $\dim(V) = n$.

Turns out these are all the same thing.

Theorem:

The set $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\} \in V$ is either ALL of the following or NONE:

1. a basis of V
2. a minimal spanning set of V
3. a maximal LI set in V
4. an independent set in V , where $\dim(V) = n$
5. a spanning set for V , with $\dim(V) = n$

These results can save a lot of time and effort.

Example: Is the following space equal to \mathbb{R}^3 ?

$$\text{Span} \left\{ \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}, \begin{bmatrix} 0 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ 1 \\ -1 \end{bmatrix} \right\}.$$

Back in the day we'd have to compare this to $[x, y, z]^T$, an arbitrary vector. Painful. However, it's a 3 dimensional space, there are three vectors, we need only confirm that they're independent. That's not easy, but it's not that hard.

$$a \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} + b \begin{bmatrix} 0 \\ 2 \\ 1 \end{bmatrix} + c \begin{bmatrix} 2 \\ 1 \\ -1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

so we get the equations

$$a + 2c = 0 \quad 2b + c = 0 \quad -a + b - c = 0$$

so $c = -2b$ and $a = 4b$ which, in the last equation, produces $-4b + b + 2b = -b = 0$, so $a = b = c = 0$ and the set is linearly independent. In a three dimensional space any three linearly independent vectors form a basis, so done, they're a spanning set.

Dimension and Subspaces

Subspaces work exactly the way you would expect with bases and dimension.

Proposition: If U is a subspace of V then $\text{Dim}(U) \leq \text{Dim}(V)$.

Proof.

This one is actually fairly simple. Any basis of U is also a linearly independent set in V , and so must have fewer or the same number of elements as a basis of V . ■

Proposition: If U is a subspace of V and $\text{Dim}(U) = \text{Dim}(V)$ then $U = V$.

Proof.

Also fairly simple. If U has the same dimension as V then a basis of U must have as many elements as a basis of V , and be linearly independent. It becomes a maximal independent set in V and so is a basis. ■

The Main Point of Bases:

Theorem:

Let $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$ be a basis for vector space V . For any $\mathbf{x} \in V$ there are *unique* coefficients a_1, \dots, a_n such that

$$\mathbf{x} = a_1\mathbf{v}_1 + a_2\mathbf{v}_2 + \dots + a_n\mathbf{v}_n.$$

Proof.

First, we can get some values a since the vectors span V . Now we need them to be unique. Assume we have another set of values:

$$\mathbf{x} = b_1\mathbf{v}_1 + b_2\mathbf{v}_2 + \dots + b_n\mathbf{v}_n$$

so

$$\mathbf{x} - \mathbf{x} = \mathbf{0} = (a_1 - b_1)\mathbf{v}_1 + (a_2 - b_2)\mathbf{v}_2 + \dots + (a_n - b_n)\mathbf{v}_n$$

which is a linear combination for the zero vector, and the set of vectors is linearly independent. As a result, each coefficient $(a_k - b_k) = 0$, so the a and b are equal. The expansions are unique. ■

Example:

Take the vector $[1, 3, 0]$ and write it in terms of the standard \mathbb{R}^3 basis:

$$\begin{bmatrix} 1 \\ 3 \\ 0 \end{bmatrix} = 1 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + 3 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + 0 \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}.$$

Next, we'll use

$$\left\{ \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \right\}.$$

We need

$$a \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} + b \begin{bmatrix} 2 \\ 1 \\ 2 \end{bmatrix} + c \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 3 \\ 0 \end{bmatrix}.$$

The last line shows $a = -b$, which combines with the second line for $c = 3$. Then $b = -1$ and $a = 1$. Final answer:

$$\begin{bmatrix} 1 \\ 3 \\ 0 \end{bmatrix} = 1 \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} + (-1) \begin{bmatrix} 2 \\ 1 \\ 2 \end{bmatrix} + 3 \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}.$$

Some Basis Related Questions:

We haven't really done enough on this subject yet, so here we go.

If $\{\mathbf{x}, \mathbf{y}, \mathbf{z}\}$ form a basis of vector space V then: does the set $\{\mathbf{x} + \mathbf{y}, \mathbf{y} + \mathbf{z}, \mathbf{z} + \mathbf{x}\}$ form a basis of V as well?

Not as hard as it looks. All you have to do is apply the standard information on bases, the definitions, the rules, etc. First: V is a vector space which has a 3 sized basis. Therefore, it is 3 dimensional. As a result, a set, like the one we're given, spans V if and only if it is linearly independent. So, we need only check linear independence.

$$\begin{aligned} a(\mathbf{x} + \mathbf{y}) + b(\mathbf{y} + \mathbf{z}) + c(\mathbf{z} + \mathbf{x}) &= \mathbf{0} \\ (a + c)\mathbf{x} + (a + b)\mathbf{y} + (b + c)\mathbf{z} &= \mathbf{0}. \end{aligned}$$

That is a linear combination. Of three Linearly Independent vectors. That means the three coefficients (scalar multipliers, whatever) HAVE to be zero. So:

$$a + c = 0 \quad a + b = 0 \quad b + c = 0.$$

That means $c = -a$, $b = -a$. Using those on the last equation gives us $-2a = 0$ so $a = 0$ then $a = b = c = 0$. So, that means that

$$a(\mathbf{x} + \mathbf{y}) + b(\mathbf{y} + \mathbf{z}) + c(\mathbf{z} + \mathbf{x}) = \mathbf{0} \implies a = b = c = 0$$

and the three vectors are LI, so they are a basis.

Now the same for $\{\mathbf{x} - \mathbf{y}, \mathbf{y} - \mathbf{z}, \mathbf{z} - \mathbf{y}\}$.

$$a(\mathbf{x} - \mathbf{y}) + b(\mathbf{y} - \mathbf{z}) + c(\mathbf{z} - \mathbf{x}) = \mathbf{0}$$

leads to

$$(a - c)\mathbf{x} + (b - a)\mathbf{y} + (c - b)\mathbf{z} = \mathbf{0}$$

so

$$a - c = 0 \quad b - a = 0 \quad c - b = 0.$$

We get $c = a$ and $b = a$. Substituting those into the last equation results in $a - a = 0$ which is true. So, we get $a = b = c = \text{free}$. Not just zero, so those three vectors are linearly dependent and not a basis.

Reducing a Spanning Set:

We do not want to do this too often, but let's take a look:

$$\left\{ \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix}, \begin{bmatrix} 0 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \right\}$$

is a spanning set of \mathbb{R}^3 . Let's reduce it to a basis. This may take a while.

$$a \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix} + b \begin{bmatrix} 0 \\ 2 \\ 1 \end{bmatrix} + c \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} + d \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix} + f \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

for

$$a + c + f = 0 \quad 2a + 2b + c + d = 0 \quad -a + b - d + f = 0.$$

$a = -c - f$. Substitute that into the other equations for

$$a = -c - f \quad 2b - c + d - 2f = 0 \quad b + c - d + 2f = 0$$

and $b = -c + d - 2f$. Substitute that into the middle equation for

$$a = -c - f \quad -3c + 3d - 6f = 0 \quad b = -c + d - 2f.$$

Finally, we get $c = d - 2f$, which we can substitute in for

$$a = -d + f \quad c = d - 2f \quad b = 0.$$

So, we can get rid of the vectors corresponding to a, c, d, f , NOT b , since it came out to zero, it is NOT variable by this solution (which happens to be correct).

So, let's ditch the second last one.

$$\left\{ \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix}, \begin{bmatrix} 0 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \right\}$$

and then look into

$$a \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix} + b \begin{bmatrix} 0 \\ 2 \\ 1 \end{bmatrix} + c \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} + d \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}.$$

So,

$$a + c + d = 0 \qquad 2a + 2b + c = 0 \qquad -a + b + d = 0$$

so $a = -c - d$, and

$$a = -c - d \qquad 2b - c - 2d = 0 \qquad b + c + 2d = 0$$

and $b = -c - 2d$ for

$$a = -c - d \qquad -3c - 6d = 0 \qquad b = -c - 2d$$

so $c = -2d$ so

$$a = d \qquad c = -2d \qquad b = 0$$

what a surprise. Anyway, get rid of a vector associated with a, c, d and you're done. Cut the last one for

$$\left\{ \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix}, \begin{bmatrix} 0 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \right\}.$$

For exercises, see the previous section. Any additional exercises will be posted as announcements on virtual campus.